

NUMERICAL AND COMPUTATIONAL METHODS

Exercise sheet 1

Exercise 1.1:

Write a function that computes the cube root of a using the second algorithm:

$$x_{n+1} = x_n - \frac{x_n^3 - a}{3x_n^2} = \frac{1}{3} \left(2x_n + \frac{a}{x_n^2} \right), \quad n = 0, 1, 2, \dots$$

How many iterations are required to obtain an accuracy of $|x^3 - a| < 10^{-6}$. Choose the initial condition $x_0 = a$ and apply the algorithm to

- (i) $a = 3.375$,
- (ii) $a = -8$,
- (iii) $a = 1331$.

Exercise 1.2:

Implement a function that computes the 2-norm of a vector $x \in \mathbb{R}^n$, i.e.,

$$\|x\| = \sqrt{\sum_{i=1}^n x_i^2}.$$

Exercise 1.3:

Define $x^{(0)} = [1, 1, 1]^\top$ and

$$A = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}.$$

Implement the following algorithm:

- (i) $\tilde{x}^{(n+1)} = Ax^{(n)}$.
- (ii) $x^{(n+1)} = \frac{1}{\|\tilde{x}^{(n)}\|} \tilde{x}^{(n)}$.
- (iii) $\alpha^{(n+1)} = \frac{x^{(n+1)\top} Ax^{(n+1)}}{x^{(n+1)\top} x^{(n+1)}}$.

Carry out the first ten iterations. What does this algorithm compute?

Exercise 1.4:

Implement the Laplace expansion to compute the determinant of a matrix $A \in \mathbb{R}^{n \times n}$. Measure the runtimes (use `tic` and `toc`) for different n and compare these results with Matlab's `det` function.

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Exercise sheet 2

Exercise 2.1:

Write a Matlab function `luSolver` that solves systems of linear equations. You can use the functions

- `luDecomposition`,
- `forwardSubstitution`,
- `backwardSubstitution`

from the lecture notes.

Exercise 2.2:

Let $H \in \mathbb{R}^{n \times n}$ be the Hilbert matrix of size n . Define $b \in \mathbb{R}^n$ by

$$b_i = \sum_{j=1}^n \frac{1}{i+j-1}.$$

- Solve the system of linear equations $Hx = b$.
- Define $\tilde{b} = b + \varepsilon e_1$, where $e_1 = [1, 0, \dots, 0]^\top$. Choose $\varepsilon = 10^{-3}$.
- Solve the perturbed system of equations $Hx = \tilde{b}$.
- Explain the results.
- Plot the runtime of the function `luSolver` for different n .

Exercise 2.3:

Let $A \in \mathbb{R}^{n \times n}$ be a symmetric positive definite matrix. Show that:

- All eigenvalues of A are positive.
- $\det(A) > 0$.
- A is invertible.
- A^{-1} is symmetric and positive definite.

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Exercise sheet 3

Exercise 3.1:

Given the interval $I = [1.75, 2]$, consider the fixed-point iteration $x_{k+1} = F(x_k)$, with $F(x) = 1 + \frac{1}{x} + \frac{1}{x^2}$.

(i) Show that F is a contraction.

(ii) Carry out the first 20 iterations using $x_0 = 1.8$. Analyze the convergence of the fixed-point iteration.

(iii) The root of which polynomial is computed here?

Hint: Let F be a differentiable function defined on an interval $I \subset \mathbb{R}$. Suppose that $|F'(x)| < M$ for all $x \in I$. Using the mean-value theorem, it holds that

$$F(x) - F(y) = F'(\xi)(x - y)$$

for some ξ between x and y . It follows that $|F(x) - F(y)| \leq M|x - y|$. That is, M is a Lipschitz constant.

Exercise 3.2:

Apply the bisection method to $f(x) = x - 1 - \frac{1}{x} - \frac{1}{x^2}$. Use the initial interval $I = [1.75, 2]$. Carry out the first ten iterations. In which interval is the root of f ?

Exercise 3.3:

Given the data points

$$\begin{array}{c|ccc} x_i & -2 & 0 & 3 \\ \hline y_i & 5 & -1 & 8 \end{array},$$

determine the Lagrange polynomials L_i and the interpolating polynomial p with $p(x_i) = y_i$. Plot your solution in Matlab and verify the results.

Exercise 3.4:

Use Newton interpolation for the data from Exercise 3.3.

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Exercise sheet 4

Exercise 4.1:

Find the polynomial p of order 3 with $p(1) = 10$, $p(2) = 26$, $p'(2) = 23$, and $p''(2) = 16$.

Exercise 4.2:

Given the interval $I = [-1, 1]$ and the inner product

$$\langle f, g \rangle = \int_{-1}^1 f(x)g(x)dx,$$

approximate the function $f(x) = \exp(x)$ using Gauss approximation. Choose the basis functions $\{1, x, x^2\}$ and solve the resulting system of linear equations. Compute the integrals with the aid of the function `quad`. Plot the results.

Exercise 4.3:

Implement the composite Simpson's rule in Matlab. Compute

$$\int_5^{10} \frac{1}{x} dx$$

for different n and compare the results with the analytical solution.

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Exercise sheet 5

Exercise 5.1:

Implement the standard fourth-order Runge–Kutta method given by the following Butcher tableau:

0				
$\frac{1}{2}$	$\frac{1}{2}$			
$\frac{1}{2}$	0	$\frac{1}{2}$		
1	0	0	1	
	$\frac{1}{6}$	$\frac{2}{6}$	$\frac{2}{6}$	$\frac{1}{6}$

Solve the initial value problems

(i) $\dot{x} = -2tx^2$, $x(0) = 1$,

(ii) $\dot{x} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} x$, $x(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$.

Compare the solutions with the analytical solutions.

Exercise 5.2:

Show that applying the aforementioned Runge–Kutta method to the ODE $\dot{x} = Ax$, where $A \in \mathbb{R}^{n \times n}$, results in a method of the form $x_{k+1} = Bx_k$. Compute the matrix B . Interpret the results.

Exercise 5.3:

Use the results from Exercise 5.2 to estimate for which $z = h\lambda$ the method is stable. Plot the stability region.